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Identification and Estimation of Structural-Change Models with Misclassification
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\begin{abstract}
Consider a simple change-point model with a binary regressor. We examine the consistency of the change-point estimator when the regressor is subject to misclassification. It is found that the time of change can always be identified. Further, special cases where the structural parameters can also be identified are discussed. Simulation evidence is provided.
\end{abstract}

\footnotetext{
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\section*{1 Introduction}

Measurement error is common in empirical data and can lead to serious estimation and inference problems. One of the earliest studies on this issue is Madansky (1959), who considers the problem of fitting a straight line when both variables are subject to errors. Levi (1973) shows that in a simple linear regression model without an intercept, if the explanatory variable is subject to errors, the regression estimates will be biased toward zero. Nelson (1995) obtains a similar attenuation bias in the multiple regression model. Chong and Lui (1998) show that the attenuation bias is nonlinear for fractionally integrated models.

The past couple of decades have witnessed a considerable effort to correct regression estimates for measurement error in the regressors. One of the commonly used methods to recover the true parameters is the instrumental-variable technique (Mahajan, 2006; Stefanski and Buzas, 1995; Fuller, 1987). Carroll et al. (2006) provide a comprehensive survey on the literature in nonlinear measurement error models. A special case of measurement error is misclassification, which occurs if the variable of interest is binary. Previous studies in misclassification include Küchenhoff et al. (2006) and Mahajan (2006), Dustmann and van-Soest (2001) and Poterba and Summers (1995, 1986).

In this paper, a structural-change model with a binary regressor measured with errors is examined. This model is different from conventional misclassification models in that it combines the problem of structural change \({ }^{1}\) and misclassification, whereas conventional misclassification models do not consider changes in parameters. For example, an individual might develop an antibody at some point in time which causes him stop responding to a medicine \({ }^{2}\). Suppose for some reason that the respondent mis-report the information about treatment, or if there exist some systematic errors, then some observations will be contaminated. The point at issue is whether the time of shift in the response function can still be consistently estimated \({ }^{3}\). It will be shown in this paper that the change point can still be identified regardless of the existence of misclassification. Further, if the nature of the misclassification is known, then all the parameters can be recovered.

The remainder of this paper is organized as follows: Section 2 presents the model. Section 3 investigates the asymptotic properties of the least squares estimators for the change point and the pre- and post-shift parameters. Five special cases are discussed. Monte Carlo experiments are conducted in Section 4. Section 5 concludes the paper.

\footnotetext{
\({ }^{1}\) There is a vast and growing literature on the structural-change models over the last decade. Recent studies by the author include Chong (2003, 2001).
\({ }^{2}\) Similar examples include the development of the antibody of an insect to insecticide, or the mutation of an virus at some point in time.
\({ }^{3}\) A related studies in this problem is Chang and Huang (1997).
}

\section*{2 The Model}

Consider the model
\[
\begin{array}{ll}
y_{t}=\alpha_{1}\left(1-x_{t}^{*}\right)+\gamma_{1} x_{t}^{*}+u_{t} & \text { for } t \leq k_{0} \\
y_{t}=\alpha_{2}\left(1-x_{t}^{*}\right)+\gamma_{2} x_{t}^{*}+u_{t} & \text { for } t>k_{0} \tag{1}
\end{array}
\]
\(t=1,2, \ldots, T\).
\(x_{t}^{*}\) is zero-one variable. For example, we let \(x_{t}^{*}=1\) if the respondent has taken the medicine at time t , and \(x_{t}^{*}=0\) otherwise.
\(\left(\alpha_{1}, \gamma_{1}\right),\left(\alpha_{2}, \gamma_{2}\right)\) are true structural parameters for \(0<t \leq k_{0}\) and \(t>k_{0}\) respectively. In this paper, we exclude the case where \(\alpha_{1}=\alpha_{2}\) and \(\gamma_{1}=\gamma_{2}\). Let \(k=[\tau T]\), where \([\cdot]\) is the greatest integer function, and \(\tau \in[0,1]\).

Suppose the true value of \(x_{t}^{*}\) is not perfectly measured and is approximated by an error-ridden measure called \(x_{t}\). We define
\[
\begin{equation*}
p=\operatorname{Pr}\left(x_{t}=0 \mid x_{t}^{*}=1\right), \tag{2}
\end{equation*}
\]
and
\[
\begin{equation*}
q=\operatorname{Pr}\left(x_{t}=1 \mid x_{t}^{*}=0\right) \tag{3}
\end{equation*}
\]

The misclassification matrix (Küchenhoff et al, 2006) is therefore equal to
\[
\Pi=\left(\begin{array}{cc}
1-q & p  \tag{4}\\
q & 1-p
\end{array}\right)
\]

Assume that:
(A1) \(\tau_{0}=\frac{k_{0}}{T} \in K \subset(0,1)\) where \(K\) is compact.
(A2) \(u_{t} \sim\) i.i.d. \(\left(0, \sigma_{u}^{2}\right), \sigma_{u}^{2}<\infty\).
(A3) \(x_{t}^{*} \sim i . i . d\). which equals 1 with probability \(a\) and equals 0 with probability \(1-a\), where \(0 \leq a \leq 1\).
(A4) \(x_{t}^{*}\) are independent of \(u_{t}\).
Assumption (A1) states that the true change point belongs to a compact set in \((0,1)\). This assumption is necessary because the least-squares estimators are not defined at the boundary of time domain. Assumptions \((A 2)-(A 4)\) describe the nature of the regressor and disturbance terms.

\section*{3 Estimation}

\subsection*{3.1 Asymptotic Behavior of the Estimators}

Model (1) can be rewritten as
\[
\begin{array}{ll}
y_{t}=\alpha_{1}+\beta_{1} x_{t}^{*}+u_{t} & \text { for } t \leq k_{0} \\
y_{t}=\alpha_{2}+\beta_{2} x_{t}^{*}+u_{t} & \text { for } t>k_{0} \tag{5}
\end{array}
\]
where
\[
\begin{equation*}
\beta_{1}=\gamma_{1}-\alpha_{1}, \tag{6}
\end{equation*}
\]
and
\[
\begin{equation*}
\beta_{2}=\gamma_{2}-\alpha_{2} . \tag{7}
\end{equation*}
\]

Note that although the covariate is misclassified, the conditional mean \(E\left(y_{t} \mid x_{t}\right)\) will still have a shift. As a result, we may still be able to estimate the true change point.

For any given \(\tau \in(0,1)\), the pre-shift estimators are defined as
\[
\begin{gather*}
\widehat{\beta}_{1 \tau}=\frac{\sum_{t=1}^{[\tau T]}\left(x_{t}-\bar{x}\right) y_{t}}{\sum_{t=1}^{[\tau T]}\left(x_{t}-\bar{x}\right) x_{t}}  \tag{8}\\
\widehat{\alpha}_{1 \tau}=\frac{1}{[\tau T]}\left(\sum_{t=1}^{[\tau T]} y_{t}-\widehat{\beta}_{1 \tau} \sum_{t=1}^{[\tau T]} x_{t}\right),  \tag{9}\\
\widehat{\gamma}_{1 \tau}=\widehat{\alpha}_{1 \tau}+\widehat{\beta}_{1 \tau} \tag{10}
\end{gather*}
\]
and the post-shift estimators are defined as
\[
\begin{gather*}
\widehat{\beta}_{2 \tau}=\frac{\sum_{t=[\tau T]+1}^{T}\left(x_{t}-\bar{x}\right) y_{t}}{\sum_{t=[\tau T]+1}^{T}\left(x_{t}-\bar{x}\right) x_{t}}  \tag{11}\\
\widehat{\alpha}_{2 \tau}=\frac{1}{T-[\tau T]}\left(\sum_{t=[\tau T]+1}^{T} y_{t}-\widehat{\beta}_{2 \tau} \sum_{t=[\tau T]+1}^{T} x_{t}\right),  \tag{12}\\
\widehat{\gamma}_{2 \tau}=\widehat{\alpha}_{2 \tau}+\widehat{\beta}_{2 \tau} . \tag{13}
\end{gather*}
\]

We define the change-point estimator as
\[
\begin{equation*}
\widehat{\tau}=\operatorname{Argmin}_{\tau \in K} S_{T}(\tau), \tag{14}
\end{equation*}
\]
where
\[
\begin{equation*}
S_{T}(\tau)=\sum_{t=1}^{[\tau T]}\left(y_{t}-\widehat{\alpha}_{1 \tau}-\widehat{\beta}_{1 \tau} x_{t}\right)^{2}+\sum_{t=[\tau T]+1}^{T}\left(y_{t}-\widehat{\alpha}_{2 \tau}-\widehat{\beta}_{2 \tau} x_{t}\right)^{2} \tag{15}
\end{equation*}
\]
is the sum of squared residuals at \(\tau\).
The final pre- and post-shift estimators are evaluated at the change-point estimate \(\widehat{\tau}\).

From the Appendix, \(\frac{1}{T} S_{T}(\tau)\) converges uniformly to a non-stochastic function \(h(\tau)\) such that \(\sup _{\tau \in[0,1]}\left|\frac{1}{T} S_{T}(\tau)-h(\tau)\right|=o_{p}(1)\), where for \(\tau \leq \tau_{0}\),
\[
\begin{equation*}
h(\tau)=h\left(\tau_{0}\right)+\Theta\left(\tau_{0}-\tau\right) \frac{1-\tau_{0}}{1-\tau} \tag{16}
\end{equation*}
\]
and
\[
\begin{align*}
h\left(\tau_{0}\right)= & \sigma_{u}^{2}+a(1-a)\left(\tau_{0} \beta_{1}^{2}+\left(1-\tau_{0}\right) \beta_{2}^{2}\right) \\
& \times\left(1-\frac{a(1-a)(1-p-q)^{2}}{(a p+(1-a)(1-q))(a(1-p)+(1-a) q)}\right)  \tag{17}\\
\Theta= & \left(\alpha_{2}-\alpha_{1}+a\left(\beta_{2}-\beta_{1}\right)\right)^{2} \\
& +\frac{\left(\beta_{2}-\beta_{1}\right)^{2} a^{2}(1-a)^{2}(1-p-q)^{2}}{(a p+(1-q)(1-a))(a(1-p)+q(1-a))}
\end{align*}
\]

Note that \(h\left(\tau_{0}\right) \geq \sigma_{u}^{2}\). Thus, under fairly general conditions, the variance of the regression error \(u_{t}\) will be over-estimated.

The first and second derivatives of \(h(\tau)\) are \(h^{\prime}(\tau)=-\Theta \frac{\left(1-\tau_{0}\right)^{2}}{(1-\tau)^{2}} \leq 0\) and \(h^{\prime \prime}(\tau)=-2 \Theta \frac{\left(1-\tau_{0}\right)^{2}}{(1-\tau)^{3}} \leq 0\) respectively. Hence, for \(\tau \leq \tau_{0}, h(\tau)\) is nonincreasing and concave. For \(\tau>\tau_{0}, h(\tau)=h\left(\tau_{0}\right)+\Theta \frac{\left(\tau-\tau_{0}\right) \tau_{0}}{\tau}, h^{\prime}(\tau)=\) \(\Theta \frac{\tau_{0}^{2}}{\tau^{2}} \geq 0\) and \(h^{\prime \prime}(\tau)=-2 \Theta \frac{\tau_{0}^{2}}{\tau^{3}} \leq 0\). Thus, for \(\tau>\tau_{0}, h(\tau)\) is non-decreasing and concave. To summarize, for all \(\tau \in[0,1], \widehat{\alpha}_{1 \tau}, \widehat{\alpha}_{2 \tau}, \widehat{\gamma}_{1 \tau}\) and \(\widehat{\gamma}_{2 \tau}\) are inconsistent estimates for \(\alpha_{1}, \alpha_{2}, \gamma_{1}\) and \(\gamma_{2}\) respectively. However, since the criterion function \(\frac{1}{T} S_{T}(\tau)\) converges uniformly to a piecewise concave function \(h(\tau)\) whose minimum takes place at the true change point, the change-point estimator is consistent.

Theorem 1: Under assumptions \((A 1)-(A 4)\), as \(T \rightarrow \infty\), we have:
\[
\begin{equation*}
\widehat{\tau} \xrightarrow{p} \tau_{0} \tag{18}
\end{equation*}
\]
and
\[
\begin{align*}
& \widehat{\alpha}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}\left(1-\lambda_{b}\right)+\gamma_{1} \lambda_{b},  \tag{19}\\
& \widehat{\gamma}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}\left(1-\lambda_{c}\right)+\gamma_{1} \lambda_{c},  \tag{20}\\
& \widehat{\alpha}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}\left(1-\lambda_{b}\right)+\gamma_{2} \lambda_{b},  \tag{21}\\
& \widehat{\gamma}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}\left(1-\lambda_{c}\right)+\gamma_{2} \lambda_{c}, \tag{22}
\end{align*}
\]
where
\[
\begin{gather*}
\lambda_{a}=\frac{a(1-a)(1-p-q)}{(a p+(1-a)(1-q))(a(1-p)+(1-a) q)},  \tag{23}\\
\lambda_{b}=\frac{a p}{a p+(1-a)(1-q)},  \tag{24}\\
\lambda_{c}=\lambda_{a}+\lambda_{b}=\frac{a(1-p)}{a(1-p)+(1-a) q} . \tag{25}
\end{gather*}
\]

Proof. See Appendix.
Note that \(\lambda_{a}\) can be negative, whereas \(\lambda_{b}\) and \(\lambda_{c}\) are between zero and one. Theorem 1 states that the change point can be identified. However, the structural estimators converge to a convex combination of the regression coefficients. In general, \(\widehat{\alpha}_{1 \widehat{\tau}}\) and \(\widehat{\alpha}_{2 \widehat{\tau}}\) will be consistent if \(\lambda_{b}=0\), while \(\widehat{\gamma}_{1 \widehat{\tau}}\) and \(\widehat{\gamma}_{2 \widehat{\tau}}\) will be consistent if \(q=0\).

An inspection of Theorem 1 suggests that it is not possible to recover the true pre- and post-shift parameters without additional information. In our case, when \(\lambda_{b}\) and \(\lambda_{c}\) are known, the true pre- and post-shift parameters can be identified. Note that if \(p, q\) and \(a\) are known, then
\[
\begin{gather*}
\frac{\lambda_{c} \widehat{\alpha}_{1 \widehat{\tau}}-\lambda_{b} \widehat{\gamma}_{1 \widehat{\gamma}}}{\lambda_{a}} \xrightarrow{p} \alpha_{1},  \tag{26}\\
\frac{\widehat{\gamma}_{1 \hat{\tau}}\left(1-\lambda_{b}\right)-\widehat{\alpha}_{1 \widehat{\tau}}\left(1-\lambda_{c}\right)}{\lambda_{a}} \xrightarrow{p} \gamma_{1},  \tag{27}\\
\frac{\lambda_{c} \widehat{\alpha}_{2 \widehat{\tau}}-\lambda_{b} \widehat{\gamma}_{2 \widehat{\tau}}}{\lambda_{a}} \xrightarrow{p} \alpha_{2},  \tag{28}\\
\frac{\widehat{\gamma}_{2 \widehat{\tau}}\left(1-\lambda_{b}\right)-\widehat{\alpha}_{2 \widehat{\tau}}\left(1-\lambda_{c}\right)}{\lambda_{a}} \xrightarrow{p} \gamma_{2} . \tag{29}
\end{gather*}
\]

In the cases where \(\lambda_{a}=0\), i.e., \(a=0, a=1\), or \(p+q=1\), the coefficients cannot be recovered.

\subsection*{3.2 Special Cases}

\subsection*{3.2.1 Case 1: \(a=0\) or \(a=1\)}

If there is only one category, two categories will be observed due to misclassification. The case where \(a=0\) is studied. When \(a=0\), we have \(\lambda_{a}=\lambda_{b}=\lambda_{c}=0\) and \(\widehat{\alpha}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}, \widehat{\gamma}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}, \widehat{\alpha}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}, \widehat{\gamma}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}\).

The case where \(a=1\) has an opposite interpretation and is therefore skipped. In general, estimators for both categories converge to the true parameters of the existing category. The coefficients of the non-existing category cannot be identified even if the values of \(p\) and \(q\) are known.

\subsection*{3.2.2 Case 2: \(p=0\) or \(q=0\)}

Consider the case where \(p=0\), which implies that \(\lambda_{b}=0\) and
\[
\lambda_{a}=\lambda_{c}=\frac{a}{a+(1-a) q} .
\]

In this case, we have
\[
\begin{gathered}
\widehat{\alpha}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}, \\
\widehat{\gamma}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}\left(1-\lambda_{c}\right)+\gamma_{1} \lambda_{c}, \\
\widehat{\alpha}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}, \\
\widehat{\gamma}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}\left(1-\lambda_{c}\right)+\gamma_{2} \lambda_{c} .
\end{gathered}
\]

Thus, the parameters for one category can be identified. The structural estimators for another category converge to a convex combination of the regression coefficients. Further, if the values of \(q\) and \(a\) are known, then all the parameters can be identified. The case for \(q=0\) has an opposite interpretation and is therefore skipped.

\subsection*{3.2.3 Case 3: \(p=1\) or \(q=1\)}

When \(p=1\), i.e., the values in one category are always wrongly measured, we have \(\lambda_{c}=0\) and
\[
\begin{gathered}
\lambda_{a}=-\frac{a}{a+(1-a)(1-q)}, \\
\lambda_{b}=-\lambda_{a}, \\
\widehat{\alpha}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}\left(1-\lambda_{b}\right)+\gamma_{1} \lambda_{b},
\end{gathered}
\]
\[
\begin{gathered}
\widehat{\gamma}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}, \\
\widehat{\alpha}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}\left(1-\lambda_{b}\right)+\gamma_{2} \lambda_{b}, \\
\widehat{\gamma}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2} .
\end{gathered}
\]

Note that the pre-shift and post-shift structural estimators are inconsistent. The estimators for the wrongly-measured category will converge to the true coefficient of another category. The estimate of the other category will be a convex combination of the true regression coefficients. If the information of \(p\), \(q\) and \(a\) are available, then all the parameters can be retrieved. The case for \(q=1\) has an opposite interpretation and is therefore skipped.

\subsection*{3.2.4 Case 4: \(p=q=1\)}

When \(p=q=1\), the dichotomous covariate is always misclassified. In this case, \(\lambda_{a}=-1, \lambda_{b}=1, \lambda_{c}=0\) and \(\widehat{\alpha}_{1 \widehat{\tau}} \xrightarrow{p} \gamma_{1}, \widehat{\gamma}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}, \widehat{\alpha}_{2 \widehat{\tau}} \xrightarrow{p} \gamma_{2}, \widehat{\gamma}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}\). Thus, the estimator for one category will converge to the coefficient of another category.

\subsection*{3.2.5 Case 5: \(p+q=1\)}

When \(p=1-q\), the two different categories are misclassified in such a way that the statistical properties of the two observed categories are identical. In this case, we have \(\lambda_{a}=0, \lambda_{b}=\lambda_{c}=a\) and
\[
\begin{aligned}
& \widehat{\alpha}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}(1-a)+\gamma_{1} a, \\
& \widehat{\gamma}_{1 \widehat{\tau}} \xrightarrow{p} \alpha_{1}(1-a)+\gamma_{1} a, \\
& \widehat{\alpha}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}(1-a)+\gamma_{2} a, \\
& \widehat{\gamma}_{2 \widehat{\tau}} \xrightarrow{p} \alpha_{2}(1-a)+\gamma_{2} a .
\end{aligned}
\]

Thus, the two pre-shift estimators converge to the same point, and the two post-shift estimators also converge to the same value. Thus, even if the coefficients of the two categories are different, this difference cannot be observed due to the common statistical properties of the two observed categories. Further, since \(\lambda_{a}=0\), the true parameters cannot be identified.

\section*{4 Monte Carlo Experiments}

This experiment verifies Theorem 1. Consider the model in Section 2:
\[
\begin{array}{ll}
y_{t}=\alpha_{1}\left(1-x_{t}^{*}\right)+\gamma_{1} x_{t}^{*}+u_{t} & \left(t=1,2, \ldots, k_{0}\right) \\
y_{t}=\alpha_{2}\left(1-x_{t}^{*}\right)+\gamma_{2} x_{t}^{*}+u_{t} & \left(t=k_{0}+1, k_{0}+2, \ldots, T\right)
\end{array}
\]

We perform the following experiment:
Let
\[
\begin{gathered}
T=5000, k_{0}=2500, \tau_{0}=\frac{k_{0}}{T}=.5 . \\
u_{t} \sim \operatorname{Nid}(0,1), \\
x_{t}^{*} \sim \text { i.i.d. Bernoulli }((1, a),(0,1-a)), \\
x_{t}=x_{t}^{*}+\varepsilon_{t} .
\end{gathered}
\]

If \(x_{t}^{*}=1\), then \(\varepsilon_{t}=-1\) with probability \(p\) and \(\varepsilon_{t}=0\) with probability \((1-p)\);
if \(x_{t}^{*}=0\), then \(\varepsilon_{t}=1\) with probability \(q\) and \(\varepsilon_{t}=0\) with probability \((1-q)\).
\(x_{t}^{*}\) and \(\varepsilon_{t}\) are independent of \(u_{t} . \lambda_{a}, \lambda_{b}\) and \(\lambda_{c}\) are defined as in Theorem 1.
For each value of \(a, p\) and \(q\), we perform a single replication. The probability limits of the estimators are calculated under Theorem 1. The results of 20 cases are reported in Table 1.

Case 1 is the case without misclassification. Case 2 to case 9 are general cases. Case 10 to case 20 are special cases. Cases 10 and 11 correspond to the first special case. Note that estimators for both categories converge to the true parameters of the existing category. The coefficients of the non-existing category cannot be identified. Cases 12 and 13 correspond to special case 2. In case 12 , when \(q=0, \gamma_{1}\) and \(\gamma_{2}\) are identified. In case 13 , when \(p=0, \alpha_{1}\) and \(\alpha_{2}\) are identified. Cases 14 and 15 correspond to special case 3 . Note that the pre-shift and post-shift structural estimators are inconsistent. The estimators for the wrongly-measured category converge to the true coefficient of another category. Case 6 is the fourth special case. The estimator for one category converges to the coefficient of another category. Cases 17 to 20 correspond to the last special case. The two pre-shift estimators converge to the same point, and the two post-shift estimators also converge to the same value. Note that the change point is consistently estimated in all cases. The simulated results in Table 1 largely conform to our theory.

Table 1: Performance of the estimators under various kinds of misclassifications
\begin{tabular}{|c|c|c|c|c|c|}
\hline Case & 1 & 2 & 3 & 4 & 5 \\
\hline (a,p,q) & \((.5,0,0)\) & (.5,.3,.4) & (.5,.4,.3) & (.5,.2,.2) & (.3,.2,.2) \\
\hline \(\left(\alpha_{1}, \alpha_{2}, \gamma_{1}, \gamma_{2}\right)\) & (2, -1, 7,9\()\) & (2, -1, 7, 9) & (2, -1, 7, 9) & (10, 15, 10, 15) & (10, 15, 10, 15) \\
\hline \(\lambda_{a}\) & 1 & 0.3030 & 0.3030 & 0.6 & 0.5348 \\
\hline \(\lambda_{b}\) & 0 & 0.3333 & 0.3636 & 0.2 & 0.0968 \\
\hline \(\lambda_{c}\) & 1 & 0.6363 & 0.6667 & 0.8 & 0.6316 \\
\hline \(\mathrm{plim} \widehat{\alpha}_{1 \widehat{\tau}}\) & 2 & 3.6667 & 3.8090 & 10 & 10 \\
\hline \(\operatorname{plim} \widehat{\alpha}_{2 \widehat{\tau}}\) & -1 & 2.3333 & 2.7796 & 15 & 15 \\
\hline plim \(\widehat{\gamma}_{1 \widehat{\tau}}\) & 7 & 5.1818 & 5.3333 & 10 & 10 \\
\hline \(\operatorname{plim} \widehat{\gamma}_{2 \widehat{\tau}}\) & 9 & 5.3995 & 5.6667 & 15 & 15 \\
\hline \(\widehat{\alpha}_{1 \widehat{\tau}}\) & 2.0588 & 3.7218 & 3.8182 & 9.9978 & 9.9590 \\
\hline \(\widehat{\alpha}_{2 \widehat{\tau}}\) & -0.9690 & 2.1099 & 2.6364 & 15.01 & 15.00 \\
\hline \(\widehat{\gamma}_{1 \widehat{\gamma}}\) & 6.9732 & 5.1542 & 5.3769 & 9.9945 & 10.02 \\
\hline \(\widehat{\gamma}_{2 \widehat{\tau}}\) & 8.9776 & 5.1455 & 5.7299 & 15.01 & 15.03 \\
\hline \(\widehat{\tau}\) & 0.5000 & 0.5060 & 0.5000 & 0.5000 & 0.5002 \\
\hline Case & 6 & 7 & 8 & 9 & 10 \\
\hline (a,p,q) & (.5,.7,.4) & (.5,.6,.6) & (.3,.2,.4) & (.3,.4,.2) & (0,.2,.2) \\
\hline \(\left(\alpha_{1}, \alpha_{2}, \gamma_{1}, \gamma_{2}\right)\) & (2, -1, 7, 9) & (2, -1, 7, 9) & (2, -1, 7, 9) & (2, -1, 7, 9) & \((10,15,15,23)\) \\
\hline \(\lambda_{a}\) & -0.1099 & -0.2 & 0.3366 & 0.3860 & 0 \\
\hline \(\lambda_{b}\) & 0.5385 & 0.6 & 0.125 & 0.1765 & 0 \\
\hline \(\lambda_{c}\) & 0.4286 & 0.4 & 0.4615 & 0.5625 & 0 \\
\hline \(\mathrm{plim} \widehat{\alpha}_{1 \widehat{\tau}}\) & 4.6923 & 5 & 2.625 & 2.8824 & 10 \\
\hline \(\operatorname{plim} \widehat{\alpha}_{2 \widehat{\tau}}\) & 4.3846 & 5 & 0.25 & 0.7647 & 15 \\
\hline \(\mathrm{plim} \widehat{\gamma}_{1 \widehat{\tau}}\) & 4.1429 & 4 & 4.3077 & 4.8125 & 10 \\
\hline \(\operatorname{plim} \widehat{\gamma}_{2 \widehat{\tau}}\) & 3.2857 & 3 & 3.6154 & 4.625 & 15 \\
\hline \(\widehat{\alpha}_{1 \widehat{\tau}}\) & 4.8293 & 4.8857 & 2.6294 & 2.8476 & 10.01 \\
\hline \(\widehat{\alpha}_{2 \widehat{\tau}}\) & 4.5149 & 4.9573 & 0.2770 & 0.7003 & 14.96 \\
\hline \(\widehat{\gamma}_{1 / \widehat{\tau}}\) & 4.0639 & 3.9620 & 4.4003 & 4.8606 & 10.04 \\
\hline \(\widehat{\gamma}_{2 \widehat{\tau}}\) & 3.0039 & 3.0244 & 3.6584 & 4.3695 & 14.99 \\
\hline \(\widehat{\tau}\) & 0.4998 & 0.4960 & 0.4970 & 0.5076 & 0.5000 \\
\hline
\end{tabular}

Table 1 cont.
\begin{tabular}{|c|c|c|c|c|c|}
\hline Case & 11 & 12 & 13 & 14 & 15 \\
\hline (a,p,q) & (1,.2,.2) & (.5,.3,0) & (.5,0,.4) & (. \(5,1, .3\) ) & (. \(5, .3,1\) ) \\
\hline \(\left(\alpha_{1}, \alpha_{2}, \gamma_{1}, \gamma_{2}\right)\) & (10, 15, 15, 23) & (2, -1, 7, 9) & (2, -1, 7, 9) & (10, 15, 15, 23) & ( \(5,8,15,23)\) \\
\hline \(\lambda_{a}\) & 0 & 0.625 & 0.7143 & -0.5882 & -0.5882 \\
\hline \(\lambda_{b}\) & 1 & 0.375 & 0 & 0.5882 & 1 \\
\hline \(\lambda_{c}\) & 1 & 1 & 0.7143 & 0 & 0.4118 \\
\hline \(\mathrm{plim} \widehat{\alpha}_{1 \widehat{\tau}}\) & 15 & 3.875 & 2 & 12.94 & 15 \\
\hline \(\operatorname{plim} \widehat{\alpha}_{2 \widehat{\tau}}\) & 23 & 2.75 & -1 & 19.76 & 23 \\
\hline \(\operatorname{plim} \widehat{\gamma}_{1 \widehat{\tau}}\) & 15 & 7 & 5.5714 & 10 & 12.06 \\
\hline \(\operatorname{plim} \widehat{\gamma}_{2 \widehat{\tau}}\) & 23 & 9 & 6.1429 & 15 & 18.29 \\
\hline \(\widehat{\alpha}_{1 \widehat{\tau}}\) & 14.89 & 3.8664 & 2.0139 & 12.89 & 14.99 \\
\hline \(\widehat{\alpha}_{2}{ }_{\tau}\) & 22.96 & 2.7719 & -1.0173 & 19.54 & 23.01 \\
\hline \(\widehat{\gamma}_{1 / \hat{\tau}}\) & 14.99 & 6.9242 & 5.5294 & 10.01 & 11.99 \\
\hline \(\widehat{\gamma}_{2 \widehat{\tau}}\) & 23.00 & 8.9698 & 6.0438 & 14.99 & 18.15 \\
\hline \(\widehat{\tau}\) & 0.5000 & 0.5000 & 0.5000 & 0.5002 & 0.5000 \\
\hline Case & 16 & 17 & 18 & 19 & 20 \\
\hline (a,p,q) & (.5,1,1) & (.5,.6,.4) & (.5,.6,.4) & (.5,.5,.5) & (.5,.3,.7) \\
\hline \(\left(\alpha_{1}, \alpha_{2}, \gamma_{1}, \gamma_{2}\right)\) & (2, -1, 7, 9) & \((10,15,15,23)\) & (2, -1, 7, 9) & (2, -1, 7, 9) & (2, -1, 7, 9) \\
\hline \(\lambda_{a}\) & -1 & 0 & 0 & 0 & 0 \\
\hline \(\lambda_{b}\) & 1 & 0.5 & 0.5 & 0.5 & 0.5 \\
\hline \(\lambda_{c}\) & 0 & 0.5 & 0.5 & 0.5 & 0.5 \\
\hline \(\mathrm{plim} \widehat{\alpha}_{1 \widehat{\tau}}\) & 7 & 12.5 & 4.5 & 4.5 & 4.5 \\
\hline \(\operatorname{plim} \widehat{\alpha}_{2 \widehat{\tau}}\) & 9 & 19 & 4 & 4 & 4 \\
\hline \(\operatorname{plim} \widehat{\gamma}_{1 \widehat{\tau}}\) & 2 & 12.5 & 4.5 & 4.5 & 4.5 \\
\hline plim \(\widehat{\gamma}_{2 \widehat{\tau}}\) & -1 & 19 & 4 & 4 & 4 \\
\hline \(\widehat{\alpha}_{1 \widehat{\tau}}\) & 6.993 & 12.47 & 4.4957 & 4.5847 & 4.3995 \\
\hline \(\widehat{\alpha}_{2 \widehat{\tau}}\) & 9.019 & 19.04 & 3.9884 & 3.7918 & 3.5123 \\
\hline \(\widehat{\gamma}_{1} \hat{\tau}\) & 1.980 & 12.35 & 4.3579 & 4.5788 & 4.4196 \\
\hline \(\widehat{\gamma}_{2 \widehat{\tau}}\) & -0.99 & 19.30 & 3.7532 & 4.1638 & 4.0422 \\
\hline \(\widehat{\tau}\) & 0.5000 & 0.5000 & 0.5110 & 0.4960 & 0.5070 \\
\hline
\end{tabular}

\section*{5 Conclusion}

In sum, this paper studies a structural-change model with the regressor being a zero-one variable subject to misclassification. This kind of model is new, in the sense that none of the previous studies in misclassification has considered the structural-change problem. The interest of this paper lies primarily in the unknown change point. Despite the fact that the data are contaminated, and the existence of a non-zero correlation between the latent variable, \(x_{t}^{*}\) and latent random error \(\varepsilon_{t}\), it is shown that the time of change can still be identified. Further, it is also shown that the true structural parameters can be extracted from the information of \(p, q\) and \(a\). Special cases of our model, as well as Monte Carlo evidence are provided to help illustrating the generic identifiability of the change point in the presence of classification errors. Our results are in line with Chong (2003), who has shown that the consistency of the change-point estimator is preserved when the regression model is misspecified.

\section*{APPENDIX}

\section*{Proof of Theorem 1:}

Let
\[
\varepsilon_{t}=x_{t}-x_{t}^{*} .
\]

Note that
\[
\begin{gathered}
E\left(x_{t}^{* 2}\right)=E\left(x_{t}^{*}\right)=1 \times \operatorname{Pr}\left(x_{t}^{*}=1\right)+0 \times \operatorname{Pr}\left(x_{t}^{*}=0\right)=a . \\
\operatorname{Var}\left(x_{t}^{*}\right)=a(1-a) .
\end{gathered}
\]
\[
E\left(\varepsilon_{t}\right)=E\left(\varepsilon_{t} \mid x_{t}^{*}=1\right) \operatorname{Pr}\left(x_{t}^{*}=1\right)+E\left(\varepsilon_{t} \mid x_{t}^{*}=0\right) \operatorname{Pr}\left(x_{t}^{*}=0\right)
\]
\[
=[p \times(-1)+(1-p) \times 0] a+[q \times(1)+(1-q) \times 0](1-a)
\]
\[
=-a p+(1-a) q .
\]
\[
\begin{aligned}
E\left(\varepsilon_{t}^{2}\right) & =E\left(\varepsilon_{t}^{2} \mid x_{t}^{*}=1\right) \operatorname{Pr}\left(x_{t}^{*}=1\right)+E\left(\varepsilon_{t}^{2} \mid x_{t}^{*}=0\right) \operatorname{Pr}\left(x_{t}^{*}=0\right) \\
& =\left[p \times(-1)^{2}+(1-p) \times 0^{2}\right] a+\left[q \times(1)^{2}+(1-q) \times 0^{2}\right](1-a) \\
& =a p+(1-a) q
\end{aligned}
\]
\[
\begin{aligned}
\operatorname{Var}\left(\varepsilon_{t}\right) & =E\left(\varepsilon_{t}^{2}\right)-E^{2}\left(\varepsilon_{t}\right)=a p+(1-a) q-(-a p+(1-a) q)^{2} \\
& =2 a p-(a p-q(1-a))(a(p+q)+1-q) .
\end{aligned}
\]
\[
\begin{aligned}
E\left(x_{t}^{*} \varepsilon_{t}\right) & =E\left(x_{t}^{*} \varepsilon_{t} \mid x_{t}^{*}=1\right) \operatorname{Pr}\left(x_{t}^{*}=1\right)+E\left(x_{t}^{*} \varepsilon_{t} \mid x_{t}^{*}=0\right) \operatorname{Pr}\left(x_{t}^{*}=0\right) \\
& =E\left(\varepsilon_{t} \mid x_{t}^{*}=1\right) \operatorname{Pr}\left(x_{t}^{*}=1\right) \\
& =[p \times(-1)+(1-p) \times 0] a \\
& =-a p .
\end{aligned}
\]
\[
\begin{aligned}
& \operatorname{Cov}\left(x_{t}^{*}, \varepsilon_{t}\right)=E\left(x_{t}^{*} \varepsilon_{t}\right)-E\left(x_{t}^{*}\right) E\left(\varepsilon_{t}\right)=-a p-a(-a p+(1-a) q)=-a(p+q)(1-a) . \\
& E\left(x_{t}\right)=E\left(x_{t}^{*}\right)+E\left(\varepsilon_{t}\right)=a(1-p)+(1-a) q . \\
& E\left(x_{t}^{2}\right)=E\left(x_{t}^{* 2}\right)+E\left(\varepsilon_{t}^{2}\right)+2 E\left(x_{t}^{*} \varepsilon_{t}\right)=a+a p+(1-a) q-2 a p=a(1-p)+(1-a) q . \\
& E\left(x_{t} \varepsilon_{t}\right)=E\left(x_{t}^{*} \varepsilon_{t}\right)+E\left(\varepsilon_{t}^{2}\right)=-a p+a p+(1-a) q=(1-a) q . \\
& \\
& \begin{array}{r}
\operatorname{Var}\left(x_{t}\right)=a(1-a)+2 a p-(a p-q+q a)(a p+1-q+q a)-2 a(p+q)(1-a) \\
=(a p+(1-a)(1-q))(a(1-p)+(1-a) q) .
\end{array}
\end{aligned}
\]

For \(\tau \in[0,1]\),
\[
\begin{gathered}
S_{* *}(\tau) \stackrel{\text { def }}{=} \frac{1}{T} \sum_{t=1}^{[\tau T]}\left(x_{t}^{*}-\overline{x^{*}}\right)^{2} \xrightarrow{p} \tau \operatorname{Var}\left(x_{t}^{*}\right), \\
S_{\varepsilon \varepsilon}(\tau) \stackrel{\text { def }}{=} \frac{1}{T} \sum_{t=1}^{[\tau T]}\left(\varepsilon_{t}-\bar{\varepsilon}\right)^{2} \xrightarrow{p} \tau \operatorname{Var}\left(\varepsilon_{t}\right)
\end{gathered}
\]
uniformly.
These results bound the variation of the stochastic insignificant terms and will be utilized in the proof of the uniform convergence result below.

Let
\[
\begin{gathered}
\lambda_{a}=\frac{a(1-a)(1-p-q)}{(a p+(1-a)(1-q))(a(1-p)+(1-a) q)}, \\
\lambda_{b}=\frac{a p}{a p+(1-a)(1-q)}, \\
\lambda_{c}=\lambda_{a}+\lambda_{b}=\frac{a(1-p)}{a(1-p)+(1-a) q},
\end{gathered}
\]
\[
\begin{aligned}
\Gamma_{1}(\tau) & =\beta_{1} \frac{\tau_{0}-\tau}{1-\tau}+\beta_{2} \frac{1-\tau_{0}}{1-\tau} \\
\Psi_{1}(\tau) & =\alpha_{1} \frac{\tau_{0}-\tau}{1-\tau}+\alpha_{2} \frac{1-\tau_{0}}{1-\tau} \\
\Lambda_{1}(\tau) & =\gamma_{1} \frac{\tau_{0}-\tau}{1-\tau}+\gamma_{2} \frac{1-\tau_{0}}{1-\tau} \\
\Gamma_{2}(\tau) & =\beta_{1} \frac{\tau_{0}}{\tau}+\beta_{2} \frac{\tau-\tau_{0}}{\tau} \\
\Psi_{2}(\tau) & =\alpha_{1} \frac{\tau_{0}}{\tau}+\alpha_{2} \frac{\tau-\tau_{0}}{\tau} \\
\Lambda_{2}(\tau) & =\gamma_{1} \frac{\tau_{0}}{\tau}+\gamma_{2} \frac{\tau-\tau_{0}}{\tau}
\end{aligned}
\]

For \(\tau \leq \tau_{0}\),
\[
\begin{aligned}
& \widehat{\beta}_{1 \tau}=\frac{\sum_{t=1}^{[\tau T]}\left(x_{t}-\bar{x}\right)\left(\alpha_{1}+\beta_{1} x_{t}^{*}+u_{t}\right)}{\sum_{t=1}^{[\tau T]}\left(x_{t}-\bar{x}\right) x_{t}} \xrightarrow[\rightarrow]{p} \beta_{1} \lambda_{a} . \\
& \widehat{\alpha}_{1 \tau}=\frac{1}{[\tau T]}\left(\sum_{t=1}^{[\tau T]}\left(\alpha_{1}+\beta_{1} x_{t}^{*}+u_{t}\right)-\widehat{\beta}_{1 \tau} \sum_{t=1}^{[\tau T]}\left(x_{t}^{*}+\varepsilon_{t}\right)\right) \\
& \xrightarrow{p} \alpha_{1}+\beta_{1}\left[a\left(1-\lambda_{a}\right)+(a p-(1-a) q) \lambda_{a}\right] \\
& =\alpha_{1}\left(1-\lambda_{b}\right)+\gamma_{1} \lambda_{b} \text {. } \\
& \widehat{\beta}_{2 \tau} \xrightarrow{p}\left(\beta_{1} \frac{\tau_{0}-\tau}{1-\tau}+\beta_{2} \frac{1-\tau_{0}}{1-\tau}\right) \lambda_{a}=\Gamma_{1}(\tau) \lambda_{a} . \\
& \widehat{\alpha}_{2 \tau}=\frac{1}{T-[\tau T]}\left(\sum_{t=[\tau T]+1}^{\left[\tau_{0} T\right]}\left(\alpha_{1}+\beta_{1} x_{t}^{*}+u_{t}\right)+\sum_{t=\left[\tau_{0} T\right]+1}^{T}\left(\alpha_{2}+\beta_{2} x_{t}^{*}+u_{t}\right)-\widehat{\beta}_{2 \tau} \sum_{t=[\tau T]+1}^{T}\left(x_{t}^{*}+\varepsilon_{t}\right)\right) \\
& \xrightarrow{p} \Psi_{1}(\tau)+\Gamma_{1}(\tau)\left[\left(1-\lambda_{a}\right) E\left(x_{t}^{*}\right)-\lambda_{a} E\left(\varepsilon_{t}\right)\right] \\
& =\Psi_{1}(\tau)+\Gamma_{1}(\tau) \lambda_{b} \\
& =\Psi_{1}(\tau)\left(1-\lambda_{b}\right)+\Lambda_{1}(\tau) \lambda_{b} . \\
& \frac{1}{T} S_{T}(\tau)=\frac{1}{T} \sum_{t=1}^{[\tau T]}\left(y_{t}-\widehat{\alpha}_{1 \tau}-\widehat{\beta}_{1 \tau} x_{t}\right)^{2}+\frac{1}{T} \sum_{t=[\tau T]+1}^{k_{0}}\left(y_{t}-\widehat{\alpha}_{2 \tau}-\widehat{\beta}_{2 \tau} x_{t}\right)^{2}+\frac{1}{T} \sum_{t=k_{0}+1}^{T}\left(y_{t}-\widehat{\alpha}_{2 \tau}-\widehat{\beta}_{2 \tau} x_{t}\right)^{2}
\end{aligned}
\]
\[
\begin{aligned}
& =\frac{1}{T} \sum_{t=1}^{[\tau T]}\left(\left(\alpha_{1}-\widehat{\alpha}_{1 \tau}\right)+\beta_{1} x_{t}^{*}+u_{t}-\widehat{\beta}_{1 \tau} x_{t}\right)^{2}+\frac{1}{T} \sum_{t=[\tau T]+1}^{k_{0}}\left(\left(\alpha_{1}-\widehat{\alpha}_{2 \tau}\right)+\beta_{1} x_{t}^{*}+u_{t}-\widehat{\beta}_{2 \tau} x_{t}\right)^{2} \\
& +\frac{1}{T} \sum_{t=k_{0}+1}^{T}\left(\left(\alpha_{2}-\widehat{\alpha}_{2 \tau}\right)+\beta_{2} x_{t}^{*}+u_{t}-\widehat{\beta}_{2 \tau} x_{t}\right)^{2} \\
& =\frac{1}{T} \sum_{t=1}^{T} u_{t}^{2}+\frac{1}{T} \sum_{t=1}^{[\tau T]}\left(\beta_{1} x_{t}^{*}-\beta_{1}\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2} \\
& +\frac{1}{T} \sum_{t=[\tau T]+1}^{k_{0}}\left(\left(\alpha_{1}-\alpha_{2}\right) \frac{1-\tau_{0}}{1-\tau}+\beta_{1} x_{t}^{*}-\Gamma_{1}(\tau)\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2} \\
& +\frac{1}{T} \sum_{t=k_{0}+1}^{T}\left(\left(\alpha_{2}-\alpha_{1}\right) \frac{\tau_{0}-\tau}{1-\tau}+\beta_{2} x_{t}^{*}-\Gamma_{1}(\tau)\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2}+o_{p}(1) \\
& \xrightarrow{p} \sigma_{u}^{2}+\tau \beta_{1}^{2} E\left(x_{t}^{*}-\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2}+\left(\tau_{0}-\tau\right) E\left(\left(\alpha_{1}-\alpha_{2}\right) \frac{1-\tau_{0}}{1-\tau}+\beta_{1} x_{t}^{*}-\Gamma_{1}(\tau)\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2} \\
& +\left(1-\tau_{0}\right) E\left(\left(\alpha_{2}-\alpha_{1}\right) \frac{\tau_{0}-\tau}{1-\tau}+\beta_{2} x_{t}^{*}-\Gamma_{1}(\tau)\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2} \\
& =\sigma_{u}^{2}+\left(\tau_{0} \beta_{1}^{2}+\left(1-\tau_{0}\right) \beta_{2}^{2}\right) E\left(x_{t}^{* 2}\right)+\left(\tau_{0}-\tau\right) \frac{1-\tau_{0}}{1-\tau}\left(\left(\alpha_{2}-\alpha_{1}\right)+\left(\beta_{2}-\beta_{1}\right) E\left(x_{t}^{*}\right)\right)^{2} \\
& +\left(\tau \beta_{1}^{2}+(1-\tau) \Gamma_{1}^{2}(\tau)\right) E\left(\lambda_{b}+\lambda_{a} x_{t}\right)^{2}-\left(\tau_{0}-\tau\right) \frac{1-\tau_{0}}{1-\tau}\left(\beta_{2}-\beta_{1}\right)^{2} E^{2}\left(x_{t}^{*}\right) \\
& -2\left[\tau \beta_{1}^{2}+(1-\tau) \Gamma_{1}^{2}(\tau)\right] E\left(x_{t}^{*}\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right) \\
& =\sigma_{u}^{2}+\left(\tau_{0}-\tau\right) \frac{1-\tau_{0}}{1-\tau}\left(\left(\alpha_{2}-\alpha_{1}\right)+\left(\beta_{2}-\beta_{1}\right) a\right)^{2} \\
& +\left(\tau_{0} \beta_{1}^{2}+\left(1-\tau_{0}\right) \beta_{2}^{2}\right) a-\left(\tau_{0}-\tau\right) \frac{1-\tau_{0}}{1-\tau}\left(\beta_{2}-\beta_{1}\right)^{2} a^{2}-\left(\tau \beta_{1}^{2}+(1-\tau) \Gamma_{1}^{2}(\tau)\right) a^{2} \\
& +\left(\tau \beta_{1}^{2}+(1-\tau) \Gamma_{1}^{2}(\tau)\right)\left[E\left(\lambda_{b}+\lambda_{a} x_{t}\right)^{2}-2 E\left(x_{t}^{*}\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)+a^{2}\right] \\
& =\sigma_{u}^{2}+\left(\tau_{0}-\tau\right) \frac{1-\tau_{0}}{1-\tau}\left(\left(\alpha_{2}-\alpha_{1}\right)+\left(\beta_{2}-\beta_{1}\right) a\right)^{2}+\left(\tau_{0} \beta_{1}^{2}+\left(1-\tau_{0}\right) \beta_{2}^{2}\right)(1-a) a \\
& -\frac{a^{2}(1-a)^{2}(1-p-q)^{2}}{(a p+(1-a)(1-q))(a(1-p)+(1-a) q)}\left(\tau \beta_{1}^{2}+(1-\tau) \Gamma_{1}^{2}(\tau)\right)
\end{aligned}
\]
\(\stackrel{\text { def }}{=} h(\tau)\).
Note that
\[
\begin{aligned}
h^{\prime}(\tau) & =-\Theta \frac{\left(1-\tau_{0}\right)^{2}}{(1-\tau)^{2}} \leq 0 \\
h^{\prime \prime}(\tau) & =-2 \Theta \frac{\left(1-\tau_{0}\right)^{2}}{(1-\tau)^{3}} \leq 0
\end{aligned}
\]
where
\[
\Theta=\left(\alpha_{2}-\alpha_{1}+a\left(\beta_{2}-\beta_{1}\right)\right)^{2}+\frac{\left(\beta_{2}-\beta_{1}\right)^{2} a^{2}(1-a)^{2}(1-p-q)^{2}}{(a p+(1-q)(1-a))(a(1-p)+q(1-a))} .
\]

For \(\tau>\tau_{0}\),
\[
\begin{gathered}
\widehat{\beta}_{1 \tau} \xrightarrow{p} \Gamma_{2}(\tau) \lambda_{a} . \\
\widehat{\alpha}_{1 \tau}= \\
\\
\quad \frac{1}{[\tau T]}\left(\sum_{t=1}^{\left[\tau_{0} T\right]} y_{t}-\widehat{\beta}_{1 \tau} \sum_{t=1}^{\left[\tau_{0} T\right]} x_{t}\right)+\frac{1}{[\tau T]}\left(\sum_{t=\left[\tau_{0} T\right]+1}^{[\tau T]} y_{t}-\widehat{\beta}_{1 \tau} \sum_{t=\left[\tau_{0} T\right]+1}^{[\tau T]} x_{t}\right) \\
= \\
= \\
= \\
= \\
\Psi_{2}(\tau)+\left[\Gamma_{2}(\tau)\left(1-\lambda_{1} E\left(x_{t}^{*}\right)+E\left(u_{t}\right)-\Gamma_{2}(\tau) \lambda_{a}\left(E\left(x_{t}^{*}\right)+E\left(\varepsilon_{t}\right)\right)\right)\right. \\
\Psi_{2}\left(\alpha_{2}+\beta_{2} E\left(x_{t}^{*}\right)+E\left(u_{t}\right)-\Gamma_{2}(\tau) \lambda_{a}\left(E\left(x_{t}^{*}\right)+E\left(\varepsilon_{t}\right)\right)\right) \\
\left.\widehat{\gamma}_{1 \tau}=\widehat{\alpha}_{1 \tau}+\widehat{\beta}_{1 \tau} \xrightarrow{p} \Psi_{2}(\tau)(1-a p+(1-a) q) \Gamma_{2}(\tau) \lambda_{a}\right)+\Lambda_{2}(\tau) \lambda_{c} . \\
\widehat{\beta}_{2 \tau} \xrightarrow{p} \beta_{2} \lambda_{a} .
\end{gathered}
\]
\[
\begin{aligned}
\widehat{\alpha}_{2 \tau}= & \frac{1}{T-[\tau T]}\left(\sum_{t=[\tau T]+1}^{T}\left(\alpha_{2}+\beta_{2} x_{t}^{*}+u_{t}\right)-\widehat{\beta}_{2 \tau} \sum_{t=[\tau T]+1}^{T}\left(x_{t}^{*}+\varepsilon_{t}\right)\right) \\
= & \alpha_{2}+\frac{1}{T-[\tau T]}\left(\beta_{2} \sum_{t=[\tau T]+1}^{T} x_{t}^{*}+\sum_{t=[\tau T]+1}^{T} u_{t}-\widehat{\beta}_{2 \tau} \sum_{t=[\tau T]+1}^{T}\left(x_{t}^{*}+\varepsilon_{t}\right)\right) \\
& \xrightarrow{p} \alpha_{2}+\beta_{2}\left(a-\frac{a(1-a)(1-p-q)}{(a p+(1-a)(1-q))(a(1-p)+(1-a) q)}(a(1-p)+(1-a) q)\right) \\
= & \alpha_{2}\left(1-\lambda_{b}\right)+\gamma_{2} \lambda_{b} .
\end{aligned}
\]
\[
\widehat{\gamma}_{2 \tau}=\widehat{\alpha}_{2 \tau}+\widehat{\beta}_{2 \tau} \xrightarrow{p} \alpha_{2}\left(1-\lambda_{c}\right)+\gamma_{2} \lambda_{c}
\]
\(\frac{1}{T} S_{T}(\tau)\)
\[
=\frac{1}{T} \sum_{t=1}^{\left[\tau_{0} T\right]}\left(\left(\alpha_{1}-\widehat{\alpha}_{1 \tau}\right)+\beta_{1} x_{t}^{*}+u_{t}-\widehat{\beta}_{1 \tau} x_{t}\right)^{2}+\frac{1}{T} \sum_{t=k_{0}+1}^{[\tau T]}\left(\left(\alpha_{2}-\widehat{\alpha}_{1 \tau}\right)+\beta_{2} x_{t}^{*}+u_{t}-\widehat{\beta}_{1 \tau} x_{t}\right)^{2}
\]
\[
\begin{aligned}
& +\frac{1}{T} \sum_{t=[\tau T]+1}^{T}\left(\left(\alpha_{2}-\widehat{\alpha}_{2 \tau}\right)+\beta_{2} x_{t}^{*}+u_{t}-\widehat{\beta}_{2 \tau} x_{t}\right)^{2} \\
& \xrightarrow{p} \sigma_{u}^{2}+(1-\tau) \beta_{2}^{2} E\left(x_{t}^{*}-\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2}+\left(\tau-\tau_{0}\right) E\left(\left(\alpha_{2}-\alpha_{1}\right) \frac{\tau_{0}}{\tau}+\beta_{2} x_{t}^{*}-\Gamma_{2}(\tau)\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2} \\
& +\tau_{0} E\left(\left(\alpha_{1}-\alpha_{2}\right) \frac{\tau-\tau_{0}}{\tau}+\beta_{1} x_{t}^{*}-\Gamma_{2}(\tau)\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)^{2} \\
& =\sigma_{u}^{2}+\frac{\left(\tau-\tau_{0}\right) \tau_{0}}{\tau}\left(\alpha_{2}-\alpha_{1}+a\left(\beta_{2}-\beta_{1}\right)\right)^{2} \\
& +\left(\left(1-\tau_{0}\right) \beta_{2}^{2}+\tau_{0} \beta_{1}^{2}\right) a-\frac{\left(\tau-\tau_{0}\right) \tau_{0}}{\tau}\left(\beta_{2}-\beta_{1}\right)^{2}\left(E\left(x_{t}^{*}\right)\right)^{2}-\left((1-\tau) \beta_{2}^{2}+\tau \Gamma_{2}^{2}(\tau)\right) a^{2} \\
& \begin{array}{l}
\left((1-\tau) \beta_{2}^{2}+\tau \Gamma_{2}^{2}(\tau)\right)\left[E\left(\lambda_{b}+\lambda_{a} x_{t}\right)^{2}-2 E\left(x_{t}^{*}\left(\lambda_{b}+\lambda_{a} x_{t}\right)\right)+a^{2}\right] \\
=\sigma_{u}^{2}+\frac{\left(\tau-\tau_{0}\right) \tau_{0}}{\tau}\left(\alpha_{2}-\alpha_{1}+a\left(\beta_{2}-\beta_{1}\right)\right)^{2}+\left(\tau_{0} \beta_{1}^{2}+\left(1-\tau_{0}\right) \beta_{2}^{2}\right)(1-a) a \\
-\frac{a^{2}(1-a)^{2}(1-p-q)^{2}}{(a p+(1-a)(1-q))(a(1-p)+(1-a) q)}\left((1-\tau) \beta_{2}^{2}+\tau \Gamma_{2}^{2}(\tau)\right) \\
\stackrel{\text { def }}{=} h(\tau) . \\
\\
h^{\prime}(\tau)=\Theta \frac{\tau_{0}^{2}}{\tau^{2}} \geq 0 . \\
h^{\prime \prime}(\tau)=-2 \Theta \frac{\tau_{0}^{2}}{\tau^{3}} \leq 0 .
\end{array}
\end{aligned}
\]

Thus, \(\frac{1}{T} S_{T}(\tau)\) converges pointwise to a piecewise concave function \(h(\tau)\), with the unique minimum at the true change point. Under assumptions \((A 1)\) to ( \(A 4\) ), the uniform convergence result follows, i.e.,
\[
\sup _{\tau \in[0,1]}\left|\frac{1}{T} S_{T}(\tau)-h(\tau)\right|=o_{p}(1)
\]

The consistency results of Chong (2001) applies. The change-point estimator is \(T\)-consistent, and the pre- and post-shift estimators are \(\sqrt{T}\)-consistent. Q.E.D.

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